Hands-On Session 2

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Goal of this session

- Adjust OpenACC directives in the example codes
- Get a first impression on speed and correctness of different approaches



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Tasks (1/4)

Take the example program from the previous hands-on. Investigate the following effects on the matmul_naive() subroutine (if you haven't done so already):

- 1. What happens if if(acc) is removed from !\$acc parallel loop if(acc)?
- 2. What happens if you replace the parallel statements with kernel statements? That is, !\$acc parallel loop if(acc) and its end directive with !\$acc kernels if(acc) and its end directive?
- 3. What happens if !\$acc parallel loop if(acc) and its end directive is moved one level up, i.e around the the do loop with it = 1, iter?



Tasks (2/4)

- 4. What is the effect of specifically targeting loops with gang and vector? Can you observe a difference between using !\$acc parallel loop gang vector if(acc) or using !\$acc parallel loop if(acc) as before and decorating all inner loops with either !\$acc loop gang, !\$acc loop vector, or !\$acc loop seq?
- 5. Can you apply collapse and still get the same result? What about performance?
- 6. Replace !\$acc parallel loop if(acc) with !\$acc parallel loop async(1) if(acc) and add !\$acc wait(1) AFTER the end of the 1, niter do-loop. What happens?



Tasks (3/4)

Take the program three_kernels.f90, which is not yet ported to GPUs.

- 7. Compile and run it on CPU to calculate a reference result. Also note the elapsed time.
- 8. Port the three kernels to GPU (one at a time) and check that the result stays the same.
- 9. Improve the performance with explicit data movement (outside the timed region)
- 10. Change the actual code (i.e. rewrite and fuse loops) to make the code even more preformant



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Tasks (4/4)

Use the example files jacobi.f90 and laplace2d.f90.

- 11. Compile and run the example on CPU.
- 12. Port it to GPU (one kernel at a time) and check the result
- 13. Improve the performance of your ported code with explicit data movement (you can also try additional optimizations).



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